Any Electronics Co.,Ltd.

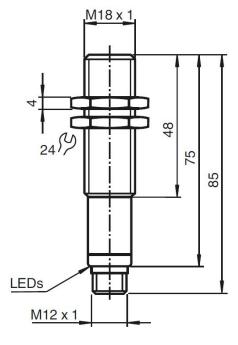
# Ultrasonic sensors

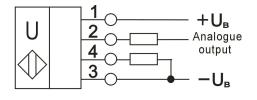
# Ultrasonic sensor

# UB1000-18GM75-I-V1

Technical data		
General Specifications		
Sensing distance	701000mm	
Adjustment range	901000mm	
Unusable area	070mm	
Standard target plate	100mm×100mm	
Transducer frequency	About 255kHz	
Response delay	About 125ms	
Indicators/Operating means		
LED blue	Power on	
LED yellow	indication of the switching state	
LED red	Flashing:program function object detected permanently red: Error Red,flashing:program function,object not detected	
<b>Electrical specifications</b>		
Operating voltage U <sub>B</sub>	1030VDC,ripple10%ss	
No-load supply current	≤45mA	
Output		
Output type	1 analogue output 420mA	
Resolution	0.35mm at max.sensing range	
Deviation of the characteristic		
curve	±1% of full-scale value	
Repeat accuracy	±0.1% of full-scale value	
Load impedance	0300 Ohm	
Temperature influence	±1.5% of full-scale value	
<b>Ambient conditions</b>		
Ambient temperature	-2570℃	
Storage temperature	-4085℃	
Mechanical specifications		
Protection grade	IP67	
Connection	Connector M12x1,4-PIN	
Material		
Housing	brass,nickel-plated	
Transducer	epoxy resin/hollow glass sphere mixture;	
XX7 * 1 .	Polyurethane foam	
Weight	60g	













#### **External synchronization**

The sensor can be synchronised by the external application of a square wave voltage. A synchronisation pulse at the synchronisation

input starts a measuring cycle. The pulse must have a duration greater than  $100 \, \mu s$ . The measuring cycle starts with the falling edge of a synchronisation pulse. A low level  $> 1 \, s$  or an open synchronisation input will result in the normal operation

of the sensor. A high level at the synchronisation input disables the sensor. Two operating modes are available:

- 1. Multiple sensors can be controlled by the same synchronisation signal. The sensors are synchronised.
- 2. The synchronisation pulses are sent cyclically to individual sensors. The sensors operate in multiplex mode.

#### **Internal synchronization**

The synchronisation connections of up to 5 sensors capable of internal synchronisation are connected to one another. When power is applied, these sensors will operate in multiplex mode.

The response delay increases according to the number of sensors to be synchronised. Synchronisation cannot be performed during TEACH-IN and vice versa. The sensors must be operated in an unsynchronised manner to teach the evaluation limits.

#### Note:

If the option for synchronisation is not used, the synchronisation input has to be connected to ground (0V) or the sensor has to be operated via a V1 cable connector (4-pin).

### Adjusting the evaluation limits

The ultrasonic sensor features an analogue output with two teachable evaluation limits. These are set by applying the supply voltage -  $U_B$  or +  $U_B$  to the TEACH-IN input. The supply voltage must be applied to the TEACH-IN input for at least 1 s. LEDs indicate whether the sensor has recognised the target during the TEACH-IN procedure. The lower evaluation limit A1 is taught with -  $U_B$ , A2 with +  $U_B$ .

Two different output functions can be set:

- 1. Analogue value increases with rising distance to object (rising ramp)
- 2. Analogue value falls with rising distance to object (falling ramp) Evaluation limits may only be specified within the first 5 minutes after Power on. To modify the evaluation limits later,

the user may specify the desired values only after a new Power On.

#### TEACH-IN rising ramp (A2 > A1)

- Position object at lower evaluation limit
- TEACH-IN lower limit A1 with U<sub>B</sub>
- Position object at upper evaluation limit
- TEACH-IN upper limit A2 with + U<sub>B</sub>

### TEACH-IN falling ramp (A1 > A2):

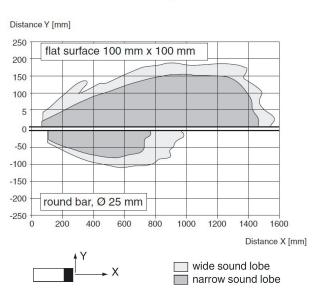
- Position object at lower evaluation limit
- TEACH-IN lower limit A2 with + U<sub>B</sub>
- Position object at upper evaluation limit
- TEACH-IN upper limit A1 with U<sub>B</sub>

Default setting

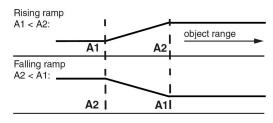
A1: unusable area

A2: nominal sensing range Mode of operation: rising ramp

## Characteristic response curve



## Programmed analogue output function





### **LED Displays**

Displays in dependence on operating mode	Red LED	Yellow LED
TEACH-IN evaluation limit		
Object detected	off	flashes
No object detected	flashes	off
Object uncertain (TEACH-IN invalid)	on	off
Normal mode (evaluation range)	off	on
Fault	on	previous state

#### Adjusting the sound cone characteristics:

The ultrasonic sensor enables two different shapes of the sound cone, a wide angle sound cone and a small angle sound cone.

### 1. Small angle sound cone

- switch off the power supply
- connect the Teach-input wire to -U<sub>B</sub>
- switch on the power supply



- the red LED flashes once with a pause before the next.
- yellow LED: permanently on: indicates the presence of an object or disturbing object within the sensing range
- disconnect the Teach-input wire from -UB and the changing is saved

## 2. Wide angle sound cone

- switch off the power supply
- connect the Teach-input wire with + U<sub>B</sub>
- switch on the power supply



- the red LED double-flashes with a long pause before the next.
- yellow LED: permanently on: indicates an object or disturbing object within the sensing range
- disconnect the Teach-input wire from + U<sub>B</sub> and the changing is saved

#### **Installation conditions**

If the sensor is installed at the environment temperature fall below 0°C, It should do well on the protective measures. In case of direct mounting of the sensor in a through hole using the steel nuts, it has to be fixed at the middle of the housing thread.